

Multiple Random Variables

Vector Random Variables

- A vector r.v. X is a function $X : S \rightarrow R^n$, where S is the sample space of a random experiment.
- Example: randomly pick up a student name from a list. $S = \{\text{all student names on the list}\}$. Let ω be a given outcome, e.g. Tom

$$\left. \begin{array}{l} H(\omega) : \text{height of student } \omega \\ W(\omega) : \text{weight of student } \omega \\ A(\omega) : \text{age of student } \omega \end{array} \right\} H, W, A \text{ are r.v.s.}$$

Let $X = (H, W, A)$, then X is a vector r.v.

Events

- Each event involving $X = (X_1, X_2, \dots, X_n)$ has a corresponding region in R^n .
- Example: $X = (X_1, X_2)$ is a two-dimensional r.v.

$$A = \{X_1 + X_2 \leq 10\}$$

$$B = \{\min(X_1, X_2) \leq 5\}$$

$$C = \{X_1^2 + X_2^2 \leq 100\}$$

Pairs of Random Variables

- Pairs of discrete random variables
 - Joint probability mass function

$$P_{X,Y}(x_j, y_k) = P\{X = x_j \cap Y = y_k\} = P\{X = x_j, Y = y_k\}$$

Obviously $\sum_j \sum_k P_{X,Y}(x_j, y_k) = 1$.

- Marginal Probability Mass Function

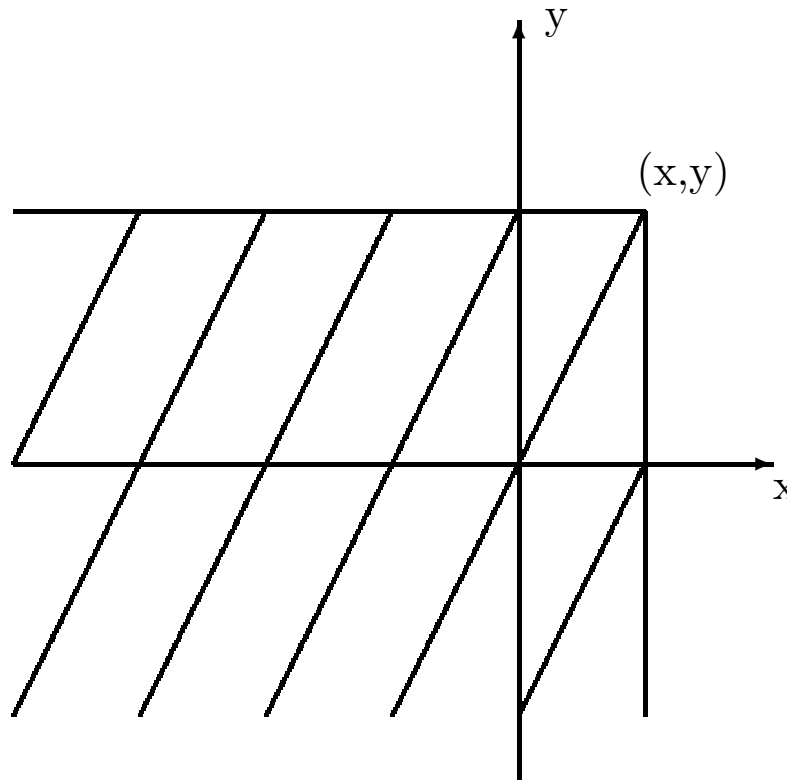
$$P_X(x_j) = P\{X = x_j\} = P\{X = x_j, Y = \text{anything}\} = \sum_{k=1}^{\infty} P_{X,Y}(x_j, y_k)$$

Similarly $P_Y(y_k) = \sum_{j=1}^{\infty} P_{X,Y}(x_j, y_k)$.

Pairs of Random Variables

- The joint CDF of X and Y (for both discrete and continuous r.v.s)

$$F_{X,Y}(x, y) = P\{X \leq x, Y \leq y\}$$



Pairs of Random Variables

- Properties of the joint CDF:

1. $F_{X,Y}(x_1, y_1) \leq F_{X,Y}(x_2, y_2)$, if $x_1 \leq x_2, y_1 \leq y_2$.

2. $F_{X,Y}(-\infty, y) = F_{X,Y}(x, -\infty) = 0$

3. $F_{X,Y}(\infty, \infty) = 1$

4. $F_X(x) = P\{X \leq x\} = P\{X \leq x, Y = \text{anything}\}$
 $= P\{X \leq x, Y \leq \infty\} = F_{X,Y}(x, \infty)$

$$F_Y(y) = F_{X,Y}(\infty, y)$$

$F_X(x), F_Y(y)$: Marginal cdf

Pairs of Random Variables

- The joint pdf of two jointly continuous r.v.s.

$$f_{X,Y}(x, y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x, y)$$

Obviously,

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx dy = 1$$

and

$$F_{X,Y}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{X,Y}(x', y') dy' dx'$$

Pairs of Random Variables

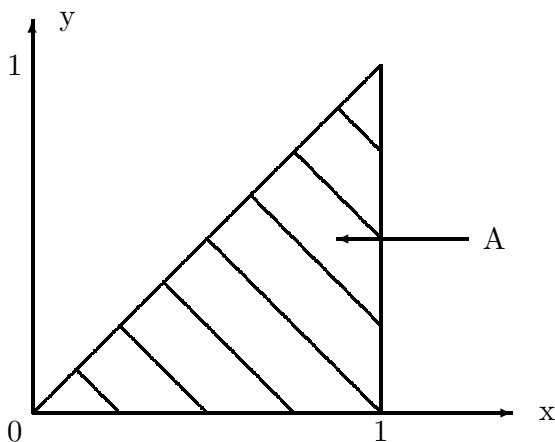
- The probability

$$P\{a \leq X \leq b, c \leq Y \leq d\} = \int_a^b \int_c^d f_{X,Y}(x, y) dy dx$$

In general,

$$P\{(X, Y) \in A\} = \int_A \int f_{X,Y}(x, y) dx dy$$

- Example:



$$\int_0^1 \int_0^x f_{X,Y}(x', y') dy' dx'$$

Pairs of Random Variables

- Marginal pdf:

$$\begin{aligned}f_X(x) &= \frac{d}{dx} F_X(x) = \frac{d}{dx} F_{X,Y}(x, \infty) \\ &= \frac{d}{dx} \left(\int_{-\infty}^x \int_{-\infty}^{\infty} f_{X,Y}(x', y') dy' dx' \right) \\ &= \int_{-\infty}^{\infty} f_{X,Y}(x, y') dy' \\ f_Y(y) &= \int_{-\infty}^{\infty} f_{X,Y}(x', y) dx'\end{aligned}$$

Pairs of Random Variables

• Example:

$$f_{X,Y}(x, y) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1, 0 \leq y \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

Find $F_{X,Y}(x, y)$

1) $x \leq 0$ or $y \leq 0$, $F_{X,Y}(x, y) = 0$

2) $0 \leq x \leq 1$, and $0 \leq y \leq 1$

$$F_{X,Y}(x, y) = \int_0^x \int_0^y 1 \, dy' dx' = xy$$

3) $0 \leq x \leq 1$, and $y > 1$

$$F_{X,Y}(x, y) = \int_0^x \int_0^1 1 \, dy' dx' = x$$

4) $x > 1$ and $0 \leq y < 1$

$$F_{X,Y}(x, y) = y$$

5) $x > 1$ and $y > 1$

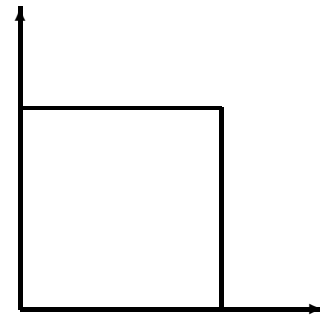
$$F_{X,Y}(x, y) = 1$$

Independence

- $P_{X,Y}(x_j, y_k) = P_X(x_j)P_Y(y_k)$, for all x_j and y_k
(discrete r.v.s)
or $F_{X,Y}(x, y) = F_X(x)F_Y(y)$ for all x and y
or $f_{X,Y}(x, y) = f_X(x)f_Y(y)$ for all x and y
- Example:

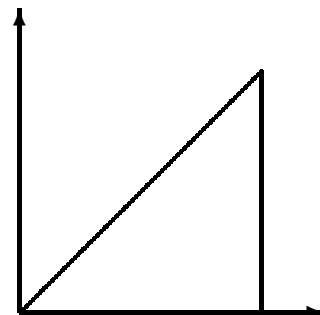
a)

$$f_{X,Y} = \begin{cases} 1 & 0 \leq x \leq 1, 0 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$



b)

$$f_{X,Y} = \begin{cases} 1 & 0 \leq x \leq \sqrt{2}, 0 \leq y \leq x \\ 0 & \text{otherwise} \end{cases}$$



Conditional Probability

- If X is discrete,

$$F_Y(y | x) = \frac{P\{Y \leq y, X = x\}}{P\{X = x\}} \quad \text{for } P\{X = x\} > 0$$

$$f_Y(y | x) = \frac{d}{dy} F_Y(y | x)$$

- If X is continuous, $P\{X = x\} = 0$

$$\underline{F_Y(y | x)} = \lim_{h \rightarrow 0} F_Y(y | x < X \leq x + h) = \lim_{h \rightarrow 0} \frac{P\{Y \leq y, x < X \leq x + h\}}{P\{x < X \leq x + h\}}$$

$$= \lim_{h \rightarrow 0} \frac{\int_{-\infty}^y \int_x^{x+h} f_{X,Y}(x', y') dx' dy'}{\int_x^{x+h} f_X(x') dx'}$$

$$= \lim_{h \rightarrow 0} \frac{\int_{-\infty}^y f_{X,Y}(x, y') dy' \cdot h}{f_X(x) \cdot h} = \underline{\frac{\int_{-\infty}^y f_{X,Y}(x, y') dy'}{f_X(x)}}$$

$$f_Y(y|x) = \frac{d}{dy} F_Y(y|x) = \frac{f_{X,Y}(x, y)}{f_X(x)}$$

Conditional Probability

- If X, Y independent,

$$f_Y(y|x) = f_Y(y)$$

- Similarly,

$$f_X(x|y) = \frac{f_{X,Y}(x, y)}{f_Y(y)}$$

So,

$$f_{X,Y}(x, y) = f_X(x) \cdot f_Y(y|x) = f_Y(y) \cdot f_X(x|y)$$

- Bayes Rule:

$$f_X(x|y) = \frac{f_X(x) \cdot f_Y(y|x)}{f_Y(y)}$$

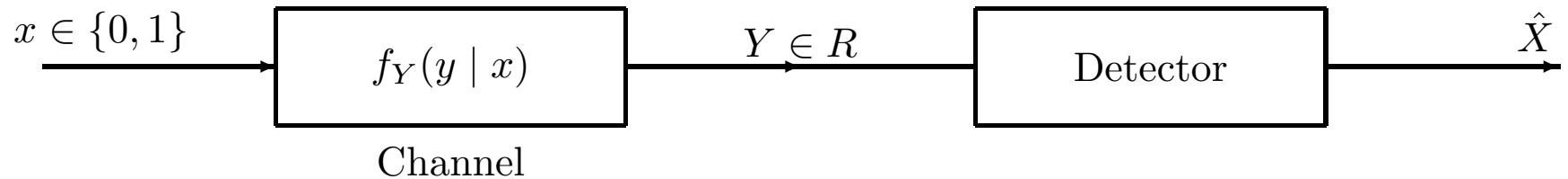
Conditional Probability

- Example: A r.v. X is uniformly selected in $[0, 1]$, and then Y is selected uniformly in $[0, x]$. Find $f_Y(y)$
- Solution:

Practice now!

Conditional Probability

- Example:



$X = 0 \longrightarrow -A$ (volts), we assume $P\{X = 0\} = P_0$

$X = 1 \longrightarrow +A$ (volts), $P\{X = 1\} = P_1 = 1 - P_0$

- Decide $\hat{X} = 0$, if $P\{X = 0 | y\} \geq P\{X = 1 | y\}$
Decide $\hat{X} = 1$, if $P\{X = 0 | y\} < P\{X = 1 | y\}$
- This is called the Maximum a posterior probability (MAP) detection.

Conditional Probability

- Binary communication over Additive White Gaussian Noise (AWGN) channel

$$f_Y(y|0) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y+A)^2}{2\sigma^2}}$$

$$f_Y(y|1) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y-A)^2}{2\sigma^2}}$$

- Apply the MAP detection, we need to find $P\{X = 0|y\}$ and $P\{X = 1|y\}$. Note here X is discrete, Y is continuous.

Conditional Probability

- Use the similar approach (considering $x < X \leq x + h$, and let $h \rightarrow 0$), we have

$$P\{X = 0|y\} = \frac{P\{X = 0\}f_Y(y|0)}{f_Y(y)}$$
$$P\{X = 1|y\} = \frac{P\{X = 1\}f_Y(y|1)}{f_Y(y)}$$

- Decide $\hat{X} = 0$, if

$$P\{X = 0|y\} \geq P\{X = 1|y\} \Rightarrow y \leq \frac{\sigma^2}{2A} \ln \frac{p_0}{p_1}$$

- Decide $\hat{X} = 1$, if

$$P\{X = 0|y\} < P\{X = 1|y\} \Rightarrow y > \frac{\sigma^2}{2A} \ln \frac{p_0}{p_1}$$

- When $p_0 = p_1 = \frac{1}{2}$:
Decide $\hat{X} = 0$, if $y \leq 0$
Decide $\hat{X} = 1$, if $y > 0$

Conditional Probability

- Prob of error:

considering the special case $p_0 = p_1 = \frac{1}{2}$

$$\begin{aligned} P_\varepsilon &= P_0 P\{\hat{X} = 1 | X = 0\} + P_1 P\{\hat{X} = 0 | X = 1\} \\ &= P_0 P\{Y > 0 | X = 0\} + P_1 P\{Y \leq 0 | X = 1\} \end{aligned}$$

$$P\{Y > 0 | X = 0\} = \frac{1}{\sqrt{2\pi}\sigma} \int_0^\infty e^{-\frac{(y+A)^2}{2\sigma^2}} dy = Q\left(\frac{A}{\sigma}\right)$$

Similarly,

$$P\{Y \leq 0 | X = 1\} = Q\left(\frac{A}{\sigma}\right)$$

$$\therefore P_\varepsilon = Q\left(\frac{A}{\sigma}\right)$$

$$A \uparrow, P_\varepsilon \downarrow \quad \sigma \uparrow, P_\varepsilon \uparrow$$

Conditional Expectation

- The conditional expectation

$$E[Y|x] = \int_{-\infty}^{\infty} y f_Y(y|x) dy$$

In discrete case,

$$E[Y|x] = \sum_{y_i} y_i P_Y(y_i|x)$$

- An important fact:

$$\underline{E[Y] = E[E[Y|X]]}$$

Proof:

$$\begin{aligned} E[E[Y|X]] &= \int_{-\infty}^{\infty} E[Y|x] f_X(x) dx = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_Y(y|x) f_X(x) dy dx \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{X,Y}(x,y) dy dx = E[Y] \end{aligned}$$

In general:

$$E[h(Y)] = E[E[h(Y)|X]]$$

Multiple Random Variables

- Joint cdf

$$F_{X_1, \dots, X_n}(x_1, \dots, x_n) = P[X_1 \leq x_1, \dots, X_n \leq x_n]$$

- Joint pdf

$$f_{X_1, \dots, X_n}(x_1, \dots, x_n) = \frac{\partial^n}{\partial x_1 \dots \partial x_n} F_{X_1, \dots, X_n}(x_1, \dots, x_n)$$

If discrete, joint pmf

$$P_{X_1, \dots, X_n}(x_1, \dots, x_n) = P[X_1 = x_1, \dots, X_n = x_n]$$

- Marginal pdf

$$f_{X_i}(x_i) = \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} f(x_1, \dots, x_n) dx_1 \dots dx_n$$

all $x_1 \dots x_n$ except x_i

Independence

- X_1, \dots, X_n are independent iff

$$F_{X_1, \dots, X_n}(x_1, \dots, x_n) = F_{X_1}(x_1) \cdots F_{X_n}(x_n)$$

for all x_1, \dots, x_n

- If we use pdf,

$$f_{X_1, \dots, X_n}(x_1, \dots, x_n) = f_{X_1}(x_1) \cdots f_{X_n}(x_n)$$

for all x_1, \dots, x_n

Functions of Several r.v.s

- One function of several r.v.s

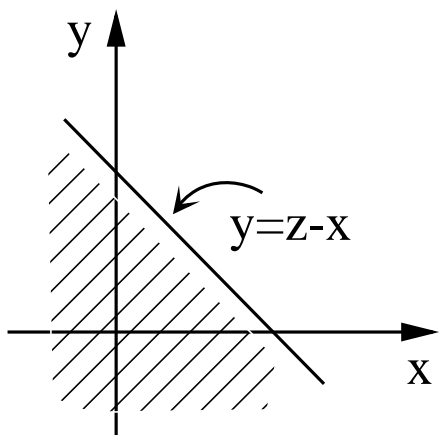
$$Z = g(X_1, \dots, X_n)$$

Let $R_z = \{\underline{x} = (x_1, \dots, x_n) \text{ s.t. } g(\underline{x}) \leq z\}$ then

$$\begin{aligned} F_z(z) &= P\{\underline{X} \in R_z\} \\ &= \int_{\underline{x} \in R_z} \dots \int f_{X_1, \dots, X_n}(x_1, \dots, x_n) dx_1 \dots dx_n \end{aligned}$$

Functions of Several r.v.s

- Example: $Z = X + Y$, find $F_z(z)$ and $f_z(z)$ in terms of $f_{X,Y}(x, y)$



$$Z = X + Y \leq z \Rightarrow Y \leq z - X$$

$$F_z(z) = \int_{-\infty}^{\infty} \int_{-\infty}^{z-x} f_{X,Y}(x, y) dy dx$$

$$f_z(z) = \frac{d}{dz} F_z(z)$$

Functions of Several r.v.s

- Example: let $Z = X/Y$. Find the pdf of Z if X and Y are independent and both exponentially distributed with mean one.

Do it yourself

Transformation of Random Vectors

- Transformation of Random Vectors

$$Z_1 = g_1(X_1 \cdots X_n) \quad Z_2 = g_2(X_1 \cdots X_n) \quad \cdots \quad Z_n = g_n(X_1 \cdots X_n)$$

The joint CDF of \underline{Z} is

$$\begin{aligned} F_{Z_1 \cdots Z_n}(z_1 \cdots z_n) &= P\{Z_1 \leq z_1, \cdots, Z_n \leq z_n\} \\ &= \int \cdots \int_{\underline{x}: g_k(\underline{x}) \leq z_k} f_{X_1 \cdots X_n}(x_1 \cdots x_n) dx_1 \cdots dx_n \end{aligned}$$

pdf of Linear Transformations

- If $\underline{Z} = A\underline{X}$, where A is a $n \times n$ invertible matrix.

$$\begin{aligned} f_{\underline{Z}}(\underline{z}) &= f_{Z_1 \dots Z_n}(z_1, \dots, z_n) \\ &= \frac{f_{X_1 \dots X_n}(x_1, \dots, x_n)}{|A|} \Bigg|_{\underline{x} = A^{-1}\underline{z}} = \frac{f_{\underline{X}}(A^{-1}\underline{z})}{|A|} \end{aligned}$$

$|A|$ is the absolute value of the determinant of A .

e.g if $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then $|A| = |ad - bc|$

pdf of General Transformations

- $Z_1 = g_1(\underline{X}), Z_2 = g_2(\underline{X}), \dots, Z_n = g_n(\underline{X})$ where $\underline{X} = (X_1, \dots, X_n)$

- We assume that the set of equations:

$$z_1 = g_1(\underline{x}), \dots, z_n = g_n(\underline{x})$$

has a unique solution given by

$$x_1 = h_1(\underline{z}), \dots, x_n = h_n(\underline{z})$$

- The joint pdf of \underline{Z} is given by

$$f_{Z_1 \dots Z_n}(z_1 \dots z_n) = \frac{f_{X_1 \dots X_n}(h_1(\underline{z}), \dots, h_n(\underline{z}))}{|J(x_1, \dots, x_n)|}$$

$$= f_{X_1 \dots X_n}(h_1(\underline{z}), \dots, h_n(\underline{z})) |J(z_1, \dots, z_n)| \quad (*)$$

where $J(x_1, \dots, x_n)$ is called the Jacobian of the transformation.

pdf of General Transformations

- The Jacobian of the transformation

$$J(x_1, \dots, x_n) = \det \begin{bmatrix} \frac{\partial g_1}{\partial x_1} & \dots & \frac{\partial g_1}{\partial x_n} \\ \dots & \dots & \dots \\ \frac{\partial g_n}{\partial x_1} & \dots & \frac{\partial g_n}{\partial x_n} \end{bmatrix}$$

and

$$J(z_1, \dots, z_n) = \det \begin{bmatrix} \frac{\partial h_1}{\partial z_1} & \dots & \frac{\partial h_1}{\partial z_n} \\ \dots & \dots & \dots \\ \frac{\partial h_n}{\partial z_1} & \dots & \frac{\partial h_n}{\partial z_n} \end{bmatrix} = \frac{1}{J(x_1 \dots x_n)} \Big|_{\underline{x}=\underline{h}(\underline{z})}$$

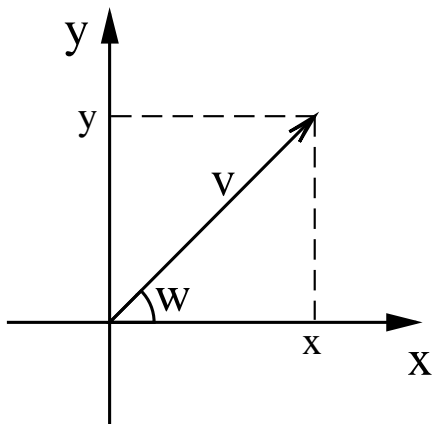
- Linear transformation is a special case of (*)

pdf of General Transformations

- Example: let X and Y be zero-mean unit-variance independent Gaussian r.v.s. Find the joint pdf of V and W defined by:

$$\begin{cases} z_1 V = (X^2 + Y^2)^{\frac{1}{2}} \\ z_2 W = \angle(X, Y) = \arctan(Y/X) \quad W \in [0, 2\pi) \end{cases}$$

- This is a transformation from Cartesian to Polar coordinates. The inverse transformation is:



$$\begin{cases} h_1 x = v \cos(w) \\ h_2 y = v \sin(w) \end{cases}$$

pdf of General Transformations

- The Jacobian

$$J(v, w) = \begin{bmatrix} \frac{dh_1/dz_1}{\cos w} & \frac{dh_1/dz_2}{-v \sin w} \\ \frac{dh_2/dz_1}{\sin w} & \frac{dh_2/dz_2}{v \cos w} \end{bmatrix} = v \cos^2 w + v \sin^2 w = v$$

- Since X and Y are zero-mean unit-variance independent Gaussian r.v.s,

$$f_{X,Y}(x, y) = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} = \frac{1}{2\pi} e^{-\frac{x^2+y^2}{2}}$$

- The joint pdf of V, W is then

$$f_{V,W}(v, w) = v \cdot \frac{1}{2\pi} e^{-\frac{(v^2 \cos^2 w + v^2 \sin^2 w)}{2}} = \frac{v}{2\pi} e^{-\frac{v^2}{2}}$$

for $v \geq 0$ and $0 \leq w < 2\pi$

pdf of General Transformations

- The marginal pdf of V and W

$$f_V(v) = \int_{-\infty}^{\infty} f_{V,W}(v, w) dw = \int_0^{2\pi} \frac{v}{2\pi} e^{-\frac{v^2}{2}} dw = v e^{-\frac{v^2}{2}}$$

for $v \geq 0$. This is called the Rayleigh Distribution.

$$f_W(w) = \int_{-\infty}^{\infty} f_{V,W}(v, w) dv = \frac{1}{2\pi} \int_0^{\infty} v e^{-\frac{v^2}{2}} dv = \frac{1}{2\pi}$$

for $0 \leq w < 2\pi$

- Since

$$f_{V,W}(v, w) = f_V(v) f_W(w)$$

$\Rightarrow V, W$ are independent.

Expected Value of Functions of r.v.

- Let $Z = g(X_1, X_2, \dots, X_n)$ then

$$E[Z] = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} g(x_1, \dots, x_n) f_{X_1 \dots X_n}(x_1, \dots, x_n) dx_1 \cdots dx_n$$

For discrete case,

$$E[Z] = \sum_{\text{all possible } \underline{x}} \cdots \sum g(x_1, \dots, x_n) P_{X_1 \dots X_n}(x_1, \dots, x_n)$$

- Example:** $Z = X_1 + X_2 + \cdots + X_n$

$$E[Z] = E[X_1 + X_2 + \cdots + X_n]$$

$$= \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} (x_1 + \cdots + x_n) f_{X_1 \dots X_n}(x_1 \cdots x_n) dx_1 \cdots dx_n$$

$$= E[X_1] + \cdots + E[X_n]$$

Expected Value of Functions of r.v.

- Example: $Z = X_1 X_2 \cdots X_n$

$$E[Z] = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} x_1 \cdots x_n f_{X_1 \cdots X_n}(x_1 \cdots x_n) dx_1 \cdots dx_n$$

If X_1, X_2, \cdots, X_n are indep.

$$E[Z] = E[X_1 X_2 \cdots X_n] = E[X_1] E[X_2] \cdots E[X_n]$$

- The (j, k) -th moment of two r.v.s X & Y is

$$E[X^j Y^k] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x^j y^k f_{X,Y}(x, y) dx dy$$

If $j = k = 1$, it is called the correlation.

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{X,Y}(x, y) dx dy$$

If $E[XY] = 0$, we call X & Y are orthogonal.

Expected Value of Functions of r.v.

- The (j, k) -th *central moment* of X, Y is

$$E \left[(X - E(X))^j (Y - E(Y))^k \right]$$

when $j = 2, k = 0, \Rightarrow Var(X)$

$j = 0, k = 2, \Rightarrow Var(Y)$

- When $j = k = 1$, it is called the covariance of X, Y

$$\begin{aligned} Cov(X, Y) &= E[(X - E(X))(Y - E(Y))] \\ &= E[XY] - E[X]E[Y] = Cov(Y, X) \end{aligned}$$

- The correlation coefficient of X and Y is defined as

$$\rho_{X,Y} = \frac{Cov(X, Y)}{\sigma_X \sigma_Y}$$

where $\sigma_X = \sqrt{Var(X)}$ and $\sigma_Y = \sqrt{Var(Y)}$.

Expected Value of Functions of r.v.

- The correlation coefficient $-1 \leq \rho_{X,Y} \leq 1$

Proof:

$$\begin{aligned} 0 &\leq E \left\{ \left(\frac{X - E[X]}{\sigma_X} \pm \frac{Y - E[Y]}{\sigma_Y} \right)^2 \right\} \\ &= 1 \pm 2\rho_{X,Y} + 1 = 2(1 \pm \rho_{X,Y}) \end{aligned}$$

- If $\rho_{X,Y} = 0$, X, Y are said to be uncorrelated.
- If X, Y are independent,
 $E[XY] = E[X]E[Y] \Rightarrow Cov(X, Y) = 0 \Rightarrow \rho_{X,Y} = 0.$
Hence, X, Y are uncorrelated.
- The converse is not always true. It is true in the case of Gaussian r.v.s (will be discussed later)

Expected Value of Functions of r.v.

- Example: θ is uniform in $[0, 2\pi)$.

Let $X = \cos \theta$ and $Y = \sin \theta$

X and Y are not independent, since $X^2 + Y^2 = 1$.

However

$$\begin{aligned} E[XY] &= E[\sin \theta \cos \theta] = E\left[\frac{1}{2} \sin(2\theta)\right] \\ &= \int_0^{2\pi} \frac{1}{2\pi} \frac{1}{2} \sin(2\theta) d\theta = 0 \end{aligned}$$

We can also show $E[X] = E[Y] = 0$. So

$$\text{Cov}(X, Y) = E[XY] - E[X]E[Y] = 0 \Rightarrow \rho_{X,Y} = 0$$

X, Y are uncorrelated but not independent.

Joint Characteristic Function

- Joint Characteristic Function

$$\Phi_{X_1 \dots X_n}(w_1, \dots, w_n) = E \left[e^{j(w_1 X_1 + \dots + w_n X_n)} \right]$$

- For two variables

$$\Phi_{X,Y}(w_1, w_2) = E \left[e^{j(w_1 X + w_2 Y)} \right]$$

- Marginal characteristic function

$$\Phi_X(w) = \Phi_{X,Y}(w, 0) \quad \Phi_Y(w) = \Phi_{X,Y}(0, w)$$

- If X, Y are independent

$$\begin{aligned} \Phi_{X,Y}(w_1, w_2) &= E[e^{jw_1 X + jw_2 Y}] \\ &= E[e^{jw_1 X}] E[e^{jw_2 Y}] = \Phi_X(w_1) \Phi_Y(w_2) \end{aligned}$$

Joint Characteristic Function

• If $Z = aX + bY$

$$\Phi_Z(w) = E[e^{jw(aX+bY)}] = \Phi_{X,Y}(aw, bw)$$

• If $Z = X + Y$, X and Y are independent

$$\Phi_Z(w) = \Phi_{X,Y}(w, w) = \Phi_X(w)\Phi_Y(w)$$

Jointly Gaussian Random Variable

- Consider a vector of random variables

$\underline{X} = (X_1, X_2, \dots, X_n)$. Each with mean $m_i = E[X_i]$, for $i = 1, \dots, n$ and the covariance matrix

$$K = \begin{bmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) & \dots & \text{Cov}(X_1, X_n) \\ \vdots & \vdots & \dots & \vdots \\ \text{Cov}(X_n, X_1) & \dots & \dots & \text{Var}(X_n) \end{bmatrix}$$

Let $\underline{m} = [m_1, \dots, m_n]^T$ be the mean vector and $\underline{x} = [x_1, \dots, x_n]^T$ where $(\cdot)^T$ denotes transpose. Then X_1, X_2, \dots, X_n are said to be the jointly Gaussian if their joint pdf is:

$$f_{\underline{X}}(\underline{x}) = \frac{1}{(2\pi)^{\frac{n}{2}} |K|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\underline{x} - \underline{m})^T K^{-1} (\underline{x} - \underline{m}) \right\}$$

where $|K|$ is the determinant of K .

Jointly Gaussian Random Variable

• For $n = 1$, let $Var(X_1) = \sigma^2$, then $f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-m)^2}{2\sigma^2}}$

• For $n = 2$, denote the r.v.s by X and Y . Let

$$\underline{m} = \begin{bmatrix} m_X \\ m_Y \end{bmatrix} \quad K = \begin{bmatrix} \sigma_X^2 & \rho_{XY}\sigma_X\sigma_Y \\ \rho_{XY}\sigma_X\sigma_Y & \sigma_Y^2 \end{bmatrix}$$

$$\text{Then } |K| = \sigma_X^2 \sigma_Y^2 (1 - \rho_{XY}^2)$$

$$K^{-1} = \frac{1}{\sigma_X^2 \sigma_Y^2 (1 - \rho_{XY}^2)} \begin{bmatrix} \sigma_Y^2 & -\rho_{XY}\sigma_X\sigma_Y \\ -\rho_{XY}\sigma_X\sigma_Y & \sigma_X^2 \end{bmatrix}$$

and

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho_{XY}^2}} \exp \left\{ -\frac{1}{2(1-\rho_{XY}^2)} \left[\left(\frac{x-m_x}{\sigma_x} \right)^2 - 2\rho_{XY} \left(\frac{x-m_x}{\sigma_x} \right) \left(\frac{y-m_y}{\sigma_y} \right) + \left(\frac{y-m_y}{\sigma_y} \right)^2 \right] \right\}$$

Jointly Gaussian Random Variable

- The marginal pdf of X :

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma_x} e^{-\frac{(x-m_x)^2}{2\sigma_x^2}}$$

The marginal pdf of Y :

$$f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma_y} e^{-\frac{(y-m_y)^2}{2\sigma_y^2}}$$

- If $\rho_{XY} = 0 \Rightarrow X, Y$ are independent.

- The conditional pdf.

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)} = \frac{\exp\left\{-\frac{1}{2(1-\rho_{XY}^2)\sigma_X^2} \left[x - \rho_{XY} \frac{\sigma_X}{\sigma_Y} (y - m_y) - m_x\right]^2\right\}}{\sqrt{2\pi\sigma_X^2(1-\rho_{XY}^2)}} \\ \sim N\left(\underbrace{\rho_{XY} \frac{\sigma_X}{\sigma_Y} (y - m_y) + m_x}_{E[X|Y]}, \underbrace{\sigma_X^2(1-\rho_{XY}^2)}_{\text{Var}(X|Y)}\right)$$

Linear Transformation of Gaussian r.v.s

• Let $\underline{X} \sim N(\underline{m}, K)$, $\underline{Y} = A\underline{X}$ then

$\underline{Y} \sim N(\underline{\hat{m}}, C)$, where $\underline{\hat{m}} = A\underline{m}$ and $C = AK A^T$

proof:

$$f_{\underline{Y}}(\underline{y}) = \frac{f_{\underline{X}}(A^{-1}\underline{y})}{|A|} = \frac{1}{(2\pi)^{\frac{n}{2}} |A||K|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (A^{-1}\underline{y} - \underline{m})^T K^{-1} (A^{-1}\underline{y} - \underline{m}) \right\}$$

Note that $A^{-1}\underline{y} - \underline{m} = A^{-1}(\underline{y} - A\underline{m}) = A^{-1}(\underline{y} - \underline{\hat{m}})$, so

$$\begin{aligned} (A^{-1}\underline{y} - \underline{m})^T K^{-1} (A^{-1}\underline{y} - \underline{m}) &= (\underline{y} - \underline{\hat{m}})^T (A^{-1})^T K^{-1} A^{-1} (\underline{y} - \underline{\hat{m}}) \\ &= (\underline{y} - \underline{\hat{m}})^T C^{-1} (\underline{y} - \underline{\hat{m}}) \end{aligned}$$

and $|A||K|^{\frac{1}{2}} = (|A|^2 |K|)^{\frac{1}{2}} = (|AK A^T|)^{\frac{1}{2}} = |C|^{\frac{1}{2}}$

$$f_{\underline{Y}}(\underline{y}) = \frac{1}{(2\pi)^{\frac{n}{2}} |C|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\underline{y} - \underline{\hat{m}})^T C^{-1} (\underline{y} - \underline{\hat{m}}) \right\} \sim N(\underline{\hat{m}}, C)$$

Linear Transformation of Gaussian r.v.s

- Since K is symmetric, it is always possible to find a matrix A s.t.

$$\Lambda = AK A^T \text{ is diagonal. } \Lambda = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix}$$

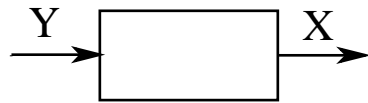
so

$$\begin{aligned} f_{\underline{Y}}(\underline{y}) &= \frac{1}{(2\pi)^{\frac{n}{2}} |\Lambda|^{\frac{1}{2}}} e^{-\frac{1}{2}(\underline{y}-\hat{\underline{m}})^T \Lambda^{-1}(\underline{y}-\hat{\underline{m}})} \\ &= \frac{1}{\sqrt{2\pi\lambda_1}} e^{-\frac{(y_1-\hat{m}_1)^2}{2\lambda_1}} \cdots \frac{1}{\sqrt{2\pi\lambda_n}} e^{-\frac{(y_n-\hat{m}_n)^2}{2\lambda_n}} \end{aligned}$$

That is, we can transform \underline{X} into n independent Gaussian r.v.s $Y_1 \cdots Y_n$ with means \hat{m}_i and variance λ_i .

Mean Square Estimation

- We use $g(X)$ to estimate Y , write as $\hat{Y} = g(X)$. The cost associated with the estimation error is $C(Y - \hat{Y})$.
e.g.



$$\begin{aligned} C(Y - \hat{Y}) &= (Y - \hat{Y})^2 \\ &= (Y - g(X))^2 \end{aligned}$$

The mean square error

$$E[C] = E[(Y - g(X))^2]$$

- Case 1: if $\hat{Y} = a$

$$E[(Y - a)^2] = E[Y^2] - 2aE[Y] + a^2 = f(a)$$

$$\frac{df}{da} = 0 \Rightarrow a^* = E[Y] = \mu_Y$$

The mean square error: $E[(Y - \mu_Y)^2] = \text{Var}[Y]$

Mean Square Estimation

- Case 2: if $\hat{Y} = aX + b$, then $E[(Y - aX - b)^2] = f(a, b)$

$$\begin{cases} \frac{\partial f}{\partial a} = 0 \\ \frac{\partial f}{\partial b} = 0 \end{cases} \Rightarrow a^* = \rho_{XY} \frac{\sigma_Y}{\sigma_X}, b^* = \mu_Y - a^* \mu_X$$

$$\Rightarrow \hat{Y} = \rho_{XY} \frac{\sigma_Y}{\sigma_X} (X - \mu_X) + \mu_Y$$

This is called the MMSE linear estimation.

- The mean square error:

$$E[(Y - \hat{Y})^2] = \sigma_Y^2 (1 - \rho_{XY}^2)$$

If $\rho_{XY} = 0$, $\hat{Y} = \mu_Y$, error = σ_Y^2 , reduces to case 1.

If $\rho_{XY} = \pm 1$, $\hat{Y} = \pm \frac{\sigma_Y}{\sigma_X} (X - \mu_X) + \mu_Y$, and error = 0

Mean Square Estimation

- Case 3: \hat{Y} is a general function of X .

$$\begin{aligned} E[(Y - \hat{Y})^2] &= E[(Y - g(X))^2] = E[E[(Y - g(X))^2|X]] \\ &= \int_{-\infty}^{\infty} E[(Y - g(x))^2|x] f_X(x) dx \end{aligned}$$

For any x , choose $g(x)$ to minimize $E[(Y - g(x))^2|X = x]$
 $\Rightarrow g^*(x) = E[Y|X = x]$

This is called the MMSE estimation.

- Example: X, Y joint Gaussian.

$$E[Y|X] = \rho_{X,Y} \frac{\sigma_Y}{\sigma_X} (X - \mu_X) + \mu_Y$$

The MMSE estimation is linear for Gaussian.

Mean Square Estimation

- Example: $X \sim \text{uniform}(-1, 1)$, $Y = X^2$. We have

$$E[X] = 0$$

$$\rho_{XY} = E[XY] - E[X]E[Y] = E[XY] = E[X^3] = 0$$

So, the MMSE linear estimation:

$$\hat{Y} = \mu_Y$$

and the error is σ_Y^2 .

The MMSE estimation:

$$g^*(x) = E[Y|X = x] = E[X^2|X = x] = x^2$$

So $\hat{Y} = X^2$ and the error is 0.